# Discussion on order of commissioning

commission\_is1 - A top level script which wraps all the commissioning scripts underneath asking the user whether to proceed to the next stage. This script should also allow starting the commissioning process from anywhere in the middle.

The commissioning of the spacecraft is divided into 3 phases:

Phase – 1:

1. Aliveness – safe and phoenix mode. Run the code depending on the spacecraft mode detected in beacon

Phase – 2:

1. Set time – DAXSS time as well as ADCS time. Should take a time stamp of the system time, compensate for UTC and upload in the satellite ADCS
2. Playback deployment data (ADCS rolls over in just 3 days)
3. Commission ADCS:
   1. Set ephemeris – A common script which will be used during Orbit operations as well
   2. Test fine pointing

Phase – 3:

1. Instrument aliveness – DAXSS and CIP both
2. Go to science
3. Adjust X123 thresholds, change modes of CIP operation

# Commissioning Test Objectives

Each test sequence is defined for 1 pass per test. Being a polar orbit, satisfactory passes are expected only twice a day at a particular ground station. Data dumps are also anticipated during some passes, so goal is to run one commissioning test sequence per day and be in normal science operations in about a week after deployment from PSLV. Target should be to complete the test sequence in the first good pass of the day. The second good pass would be a backup in case the test sequence does not complete during the first pass. Each test script should contain a FINISH section to which the operator should jump if the pass nears an end (<2 minutes before end of pass).

|  |  |  |
| --- | --- | --- |
| **Test Sequence** | **Objective** | **~Time to complete script with no catches (should be < 5 min)** |
| 1 | Do aliveness test, change SD card beacon rate to slower value (commission\_aliveness\_safe / commission\_aliveness\_phoenix) | 3 minutes |
| 2 | Set spacecraft and ADCS time, set ephemeris and set to fine pointing (commission\_set\_adcs\_time, commission\_set\_daxss\_time, commission\_set\_ephemeris) | 3 minutes |
| 3 | Commission ADCS – test fine pointing  (commission\_adcs\_fine\_point) | 5 minutes |
| 4 | Test Sband reception – downlink beacon partition | 2 minutes |
| 5 | Download beacon deployment data - 12 hrs worth of deployment data to download from UHF takes about 9792 seconds, hence downloading from SBand is more appropriate  (commission\_playback\_dep\_data) | 5 minutes |
| 6 | Do instrument aliveness test in safe mode  (commission\_daxss\_aliveness, commission\_cip\_aliveness) |  |
| 7 | Go to science mode (commission\_scic\_mode, commission\_scid\_mode) |  |
| 8 | Adjust X123 threshold and set CIP opmode  (commission\_adjust\_x123\_thresh, commission\_set\_cip\_opmode) | Multiple days including analysis |

# Pass / Safety Priorities

1. Battery voltage ≥ 7.0 V
2. Sun point status
3. Bus subsystems healthy + commands functional
4. Instruments healthy

# Personnel Roles and Responsibilities

## Roles

* MOM: Mission Operations Manager
  + Amal Chandran
  + Rick Kohnert – Deputy MOM
* Commissioning Operators – basically run commissioning scripts on Hydra
  + Dhruva Anantha Dutta – lead for phase 1 scripts
  + Aman Naveen – lead for phase 2 scripts
  + Aroshish – lead for DAXSS instrument
  + Aakash – lead for CIP instrument
* Radio Comm / Antenna and rotator controller
  + Joji – lead for ground station radios and PCs
* BCT XACT ADCS
  + Amal – lead & BCT team remotely
* Planning (playback) Software
  + Mayuresh and Dhruva – development & test
  + Dhruva & Aman for weekly / daily planning
* Post-pass Data Processing
  + Amal - CIP data
  + Robert – DAXSS data

## Script Developers

* Mayuresh Sarpotdar
  + commission\_aliveness\_phoenix
  + commission\_aliveness\_safe
  + commission\_cdh\_tlm\_check
  + commission\_eps\_tlm\_check
  + commission\_comm\_tlm\_check
  + commission\_adcs\_tlm\_check
  + commission\_act\_deployables
  + commission\_reduce\_launch\_delay
  + commission\_set\_adcs\_time
  + commission\_set\_daxss\_time
  + commission\_set\_ephemeris
  + commission\_adcs\_fine\_point
  + commission\_scic\_mode
  + commission\_scid\_mode
  + commission\_playback\_dep\_data(partition\_id, write\_pointer)
* Robert Sewell
  + commission\_daxss\_aliveness
  + commission\_science\_mode\_DAXSS
  + commission\_x123\_threshold
* Amal Chandran
  + commission\_cip\_aliveness
  + commission\_science\_mode\_CIP
  + commission\_change\_mode\_CIP

## Display Monitoring

* Hydra Machine (Dhruva/ Aman)
* UHF PC (Aman/ Dhruva)
  + UHF TMTC Gnuradio
* UHF Antenna controller (Ramana/ Aroshish)
  + Antenna controller WISP DDE
  + SDR Console to track the satellite
* SBand PC (Joji)
  + SBand Telemetry Gnuradio
  + SBand antenna controller

# Pre-Pass Procedure

1. Make sure that MinXSS FM-2 is not running, and that the roof antenna is connected to the radio
2. Print a blank copy of [8090-002 MinXSS Pass Sheet template](https://drive.google.com/open?id=1sXt8pgKD0enD6oNBARai5x0Ux4fv36d-SyW16cHusVE) or be prepared to fill it out electronically and print it after the pass
3. Ensure SatPC32 is running on Rocket6 computer (HP 21”)
   1. Ensure that rotor and frequency control are enabled in the upper left (should read R**+** and C**+**)
   2. Ensure SatPC32 is configured to point to and use MinXSS’s frequency (437.345 MHz) (see bottom right, should be configured for “A”)
4. Review all scripts that need to be run this pass
5. Prepare ISIS playback script OR be ready to use playback\_all\_data\_last\_24\_hours.prc, which plays back the last 24 hours of data in 5 minutes (10-min cadence for HK and SCI, 20 min for ADCS). Ensure that playback script is appropriate for the pass type (e.g., when commissioning ADCS, we’ll want an ADCS-specific pass ready, and when doing pre-science commissioning we won’t want SCI data)
   1. If something's wrong from previous data, prepare a custom script to downlink data to address that. This script should be stored in post-pass.
   2. If nothing was wrong in previous data, and if this pass is ***not***the longest pass of the day, prepare a custom script to downlink specialized data with higher cadence (e.g., more ADCS if we're not yet in science mode). This script should be stored in post-pass.
   3. If nothing was wrong in previous data, and if this ***is*** the longest pass of the day, run playback\_all\_data\_last\_24\_hours.prc. This script should be stored in post-pass even though it’s identical every time so that we have a consistent historical record of .prc files run.
6. Launch ISIS on OPS-1 computer (WinD2791 Dell 27”)
   1. Ensure relevant Display Pages opened: HK, SCI, playback, command buttons, param dump, and command status (the last is opened from View menu). Also ensure the critical telemetry window is open on the second monitor.
      1. This can all be done by doing “load\_dc” if it fails to do it on its own when opening
7. Open powerpoint on the OPS-1 computer. It will prompt you for a template. Go to Personal, and select the MinXSS template. Fill out the title slide and then you can minimize powerpoint.
8. Launch IDL on DataProcessing computer (iMac MacL68) and start IDL real time plotting routines
   1. minxss\_trunk/real\_time/ and then select the code as appropriate: e.g., minxss\_real\_time\_socket\_read\_wrapper\_adcs or minxss\_real\_time\_socket\_read\_wrapper\_sci
9. Ensure we understand any coordination plans we’ve made with CADRE, and either start the pass late or end it early if necessary
10. Get screenshare and communications set up for BCT.
    1. Turn on join.me for screenshare on OPS-2. Help BCT get projector running with the shared screen in LSTB 299 auditorium.
    2. Get the wireless phone from the Kepler MOC and establish phone call between it and the phone in the 299 auditorium. The MOC phone number is 303-492-4211.

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# During Pass

1. Run *hello\_minxss.prc* script to establish communications with MinXSS ([see here if issues communicating during pass](#_cp6rvtbsaajg))
2. Once telemetry is displayed in ISIS, resize the windows slightly so that the spacing fixes itself
3. Take a screenshot of the HK window by pressing “windows-key + print screen”, which will save a screenshot to the directory OPS\Pictures\Screenshots.
4. Verify the critical telemetry is in-bounds (if not, see “MinXSS Recovery Instructions”). Note that Test 1 *will* proceed if the spacecraft is in Phoenix mode.
5. Proceed to the Test instructions as appropriate: [Test 1](#_k2cmia3kh6em), [Test 2](#_rszln8o3n3ib), [Test 3](#_2o4rg3s8r81l), [Test 4](#_2aly10gvaeq8), [Test 5](#_e3k22afddf)

**Note**: Do notx-out of ISIS windows to close them because ISIS will crash. Just minimize windows if needed.

# If Issues Communicating During Pass

Follow the steps below if you do not receive autonomous beacons or response from commanded *issue\_hk\_packet*, which is what the *hello\_minxss.prc* script does and should be run at the beginning of every pass

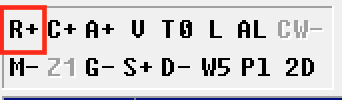
**Note 1**: Communication issues are especially likely during the first pass

**Note 2**: In safe mode, the spacecraft won’t be trying to keep the antenna pointed optimally[[1]](#footnote-1), but default roll rate is ~0.2º/sec[[2]](#footnote-2) (read, slow), so we’ll be stuck in a gain null or not for a long time

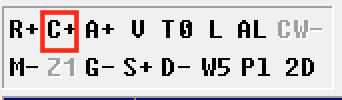
**Note 3:** The spacecraft will not be on (and therefore the antenna will not deploy) for the first 30 minutes after it leaves the ISS, so if we get a pass in that window we should expect comms not to work

1. Make sure the Kenwood radio volume is up so beacons can be heard

2. Tune ground antenna pointing

* 1. First try switching SatPC to use the CADRE TLE
     1. In the lower right of SatPC, double click “B”, which is the second loaded satellite, and should have been set up for CADRE
  2. Have a person dedicated to manual control of the Elevation-Azimuth Dual Controller G-5500 box 
  3. Disable SatPC automatic control of rotors
     1. Upper left of SatPC, change R+ to R- 
  4. While ISIS continues to run the *hello\_minxss.prc* script, sweep slowly in elevation and azimuth
  5. If a beacon is heard from the Kenwood radio, note the discrepancy from what SatPC expects at that moment
  6. Continue manual control of the ground antenna pointing throughout the pass, with SatPC as a guide
  7. After the pass, note the discrepancy and adjust SatPC accordingly (TLE improvement, antenna pointing offsets)

3. Tune radio frequency

* 1. Have a person dedicated to manual control of the Kenwood radio
  2. Disable SatPC automatic radio tuning
     1. Upper left of SatPC, change C+ to C- (CAT control) 
  3. Tune radio frequency slowly, noting the below
     1. The best frequency during ground testing was 437.345 MHz
     2. MinXSS radio has bandwidth of 0.15 MHz
     3. CADRE is using 437.485 MHz with the same radio
     4. Max Doppler shift is 0.003432 MHz
  4. If a beacon is heard from the Kenwood radio, note the discrepancy from what SatPC expects at that moment (**Note:** If the Kenwood makes sound but we don’t get telemetry data, then it’s from CADRE! Don’t tune the frequency/location to CADRE!)
  5. Continue manual control of the frequency throughout the pass, with SatPC as a guide (to compensate for Doppler)
  6. Consider turning off SatPC Doppler correction (CSSWE had to at first)

4. Reset the flight radio by command: *power\_cycle\_comm*

* 1. Radio is known to lock up and give intermittent telemetry out if the *comm\_amp\_level* command is sent, cause unknown, so space environment could potentially cause this lock up. **Note**: the lockup also causes the radio temperature to rise dangerously, reset fixes it

5. Plug Scott Palo’s spectrum analyzer in the pipe between the antenna and the radio

* 1. Make sure Scott Palo or someone who knows how to use it is present to see if any signal is coming through

6. If all else fails, consider rebooting the CDH with command: *trigger\_watchdog\_reset*

1. Only take this drastic action if we’re sufficiently separated from CADRE

7. Finally, keep trying ?? days for the fishing line to degrade (in this case we’re assuming the antenna did not deploy)

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# Operator Actions If Telemetry Point Out of Limits

These are actions for the operator to take in response to any individual telemetry point being out of limits. There aren’t a whole lot of commands that can influence things, so the telemetry points have been grouped according to common operator responses.

|  |  |  |  |
| --- | --- | --- | --- |
|  | HK Monitor | Safe Range | Action if Out of Range |
| Mode Issues | CDH Mode | Science (Safe) | Phoenix: Wait until battery is charged or force to Safe mode  Safe: Wait until battery is charged or configure X123 to power cycle off during eclipse  Scripts: commission\_aliveness\_phoenix, comission\_aliveness\_safe |
| XACT Mode | Fine Point (Sun Point) | ADCS Off: Force to Safe mode or turn on ADCS  Sun Point / Safe: Wait until Science mode or force to Fine Point mode  Scripts: commission\_set\_ephemeris, commission\_science\_mode, commission\_test\_fine\_point |
| Power Issues | Battery Voltage | 7.0 - 8.4 V | Shed power: X123, SPS |
| Discharge Current | 0-2000 mA | Low Current: Identify which subsystem is off and turn it on (or change Mode)  High Current: Identify which subsystem is cause of high current and power cycle it. |
| Charge Current | 0-2000 mA |
| 3.5 V Current | 200-400 mA |
| 5.0 V Current | 0-1500 mA |
| Temp Issues | Battery Temperature | 2-8 C | Heater Issue: Disable / Enable battery heater and reset its set point temperature  Too Hot: wait for orbit change or power cycle X123 during eclipse |
| X123 Det Temperature | 220-235 K | Set and Verify X123 detector temperature setting |
| X123 Bd Temperature | 10-40 C | Too Hot: power cycle X123 during eclipse |
| Radio Temperature | 10-40 C | Too Hot: power cycle COMM if L1-I radio is hung |
| Science & Pointing Issues | SPS Angle X | -1000 to 1000 | First verify that S/C is in the Sun.  Not on Sun: identify and fix ADCS pointing issue  (see Mode Issue scripts listed above)  X123 Counts high in eclipse: adjust THFA / THSL  Script: commission\_x123\_thresholds |
| SPS Angle Y | -1000 to 1000 |
| SPS Signal |  |
| XP Signal |  |
| Dark Diode Signal |  |
| X123 Slow Count |  |
| X123 Fast Count |  |

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# Test 1: Do Aliveness Test

(1.1a) If in PHOENIX (i.e. you wknow it’s been <30 min since deployment) then

start commission\_aliveness\_phoenix

hello\_minxss

route\_hk\_pkt Route 5 ; repeat until see command success

call cdh\_tlm\_check

call eps\_tlm\_check

call comm\_tlm\_check

set\_spacecraft\_time

route\_hk\_pkt Route 1

Also, see “MinXXS Recovery Instructions” under Mode Issues and Power Issues

(1.1b) Else if in SAFE then (Note: this is safe to run in phoenix)

start commission\_aliveness\_safe

hello\_minxss

route\_hk\_pkt Route 3 ; repeat until see command success

set\_spacecraft\_time\_now ; repeat until see command success

call cdh\_tlm\_check

call eps\_tlm\_check

call comm\_tlm\_check

call adcs\_tlm\_check

call sps\_tlm\_check

call adcs\_aliveness

route\_hk\_pkt Route 5

(1.2) Optionally do playback of data if Battery Volt > 7.0 V (or Wait until next pass)

DO NOT RUN IF WITHIN LOS - 3 MINUTES

call playback\_deployment\_data(except science) \*\*\*\*NEEDS FIXING\*\*\*\*

REPEAT TEST 1 UNTIL IN SAFE MODE WITH SUN POINT

Critical for First Pass

1. HK packets received - prepare to adjust radio frequency
2. ADCS Mode is in SUN\_POINT and Sun Body X is ~ 1.0
3. SA 1-3 Power is > 7 W (if in sun)

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# Test 1.5: Disable Auto-Deploy

1. Verify that the antenna and solar arrays are deployed
   1. Antenna is verified to be open by the fact that communication is working at all
   2. Solar arrays open can be verified by looking at the 3 solar panel powers (W) in the critical telemetry panel during an insolated period
2. Send the cancel\_ant\_deploy\_retry command
3. Verify the command accept counter increments, if not, keep sending the command

# Test 2: Configure and verify ADCS fine point

(2.1) start commission\_set\_adcs\_time ; repeat until success

(2.2) start commission\_set\_ephemeris

* adcs\_InitPosVelUtcGreg Year Mon Day Hour Min Sec millisec PosX PosY PosZ VelX VelY VelZ
  + e.g., adcs\_InitPosVelUtcGreg Year 15 Mon 3 Day 24 Hour 15 Min 28 Sec 0 millisec 0 PosX 7000 PosY 0 PosZ 0 VelX 0 VelY 0 VelZ 7.7
* adcs\_SetAttitude Q\_b\_wrt\_i\_1 Q\_b\_wrt\_i\_2 Q\_b\_wrt\_i\_3 Q\_b\_wrt\_i\_4
  + e.g., adcs\_SetAttitude Q\_b\_wrt\_i\_1 0 Q\_b\_wrt\_i\_2 0 Q\_b\_wrt\_i\_3 0 Q\_b\_wrt\_i\_4 1
* tlmwait MINXSSADCSAttitudeValid\_Tlm\_All == 1 or YES or VALID
* tlmwait MINXSSADCSRefsValid\_Tlm\_All == 1 or YES or VALID
* tlmwait MINXSSADCSTimeValid\_Tlm\_All == 1 or YES or VALID

(2.3) start commission\_test\_fine\_point

* Is MinXSS on dayside of orbit? NO → (1.3)
* Is ADCS in Sun-Point mode and within 10 deg of Sun ? NO → (1.3)
  + Verify by checking ADCS packet 4(?) for present attitude error
  + Verify by plotting N seconds of SPS position data
* adcs\_GotoFineSunPoint (parameters = enable, 6, 1, 2, 0)
* tlmwait fine\_sun\_point
* playback data later to analyze performance

(2.4) Optionally do playback of data if Battery Volt > 7.0 V (or Wait until next pass)

call playback\_all\_data\_last\_24\_hours (except science)

REPEAT TEST 2 UNTIL SCRIPT SUCCESS

# Test 3: Do instrument aliveness (in science mode)

(3.1) Is MinXSS on dayside of orbit? NO → (1.3)

(3.2) Is ADCS in Sun-Point mode and within 10 deg of Sun ? NO → (1.3)

* Verify by checking ADCS packet 3 (Display Page → MinXSS\_ADCS\_3) for “Sun Point Angle Error” in bottom right (TODO: Update to point to “critical ADCS panel”
* Verify by plotting N seconds of SPS position data

(3.3) Is “SA/Battery V” > 7.5 V? NO → (1.3)

start commission\_instrument\_aliveness

route\_hk\_pkt Route 3 ; repeat until see command success

call sps\_tlm\_check

switch\_power\_x123 PowerDirection 1

call x123\_tlm\_check

switch\_power\_x123 PowerDirection 0

route\_hk\_pkt Route 5

(3.4) Optionally do playback of data if Battery Volt > 7.0 V (or Wait until next pass)

call playback\_all\_data\_last\_24\_hours (except science)

REPEAT TEST 3 UNTIL IN FINE POINT

# Test 4: Go to Science Mode

(4.1) Is MinXSS on dayside of orbit? NO → (1.3)

(4.2) Is ADCS in fine reference mode and within 5 deg of Sun ? NO → (1.3)

* Verify by checking critical telemetry data window for “Sun Point Angle Error”
* Verify by plotting N seconds of SPS position data

(4.3) Is Battery Volt > 7.5 V? NO → (1.3)

start commission\_science\_mode

route\_hk\_pkt Route 3 ; repeat until see command success

set\_mode\_sci

call sps\_tlm\_check

call x123\_tlm\_check

route\_hk\_pkt Route 5

REPEAT TEST 4 UNTIL IN SCIENCE MODE

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# Test 5: Adjust X123 thresholds

THIS TEST IS LIKELY TO BE A MANUAL THRESHOLD SELECTION RATHER THAN AUTOMATED. SPEAK TO SCIENTISTS TO DECIDE HOW TO PROCEED.

(5.1) Is MinXSS in eclipse? NO → (1.3)

(5.2) start commission\_x123\_thresholds

route\_hk\_pkt Route 3

loop until x123 normalized slow counts in hk < 10

Initial THSL = 1.0

THSL+= THSL + 0.1

loop until x123 normalized fast counts in hk < 10

Initial THFA = 16.0

THFA += 0.5

(5.3) Verify by analysis

REPEAT TEST 5 UNTIL COUNTS IN ECLIPSE ARE ≤ 10 cps

# Post-Pass Procedure

1. Fill out the pass sheet (by hand or electronically and then print it)
2. Move the screenshots from OPS\Pictures\Screenshots to the powerpoint slides that you set up in the [Pre-Pass Procedure](#_v64yqlaq5mef).
3. 3 hole punch these sheets and put them in the MinXSS Pass Binder
4. Close ISIS (File -> Exit)
5. Edit the filenames of all scripts run during the pass to end with \_*yyyymmdd\_Pass#\_ran*, for example playback\_all\_data\_last\_24\_hours\_20160211\_Pass3\_ran.prc.
6. Copy everything in the ISIS run directory (03 ISIS\Rundirs\yyyy\_doy\_hh\_mm\_ss) that ISIS just generated is in the shared Dropbox folder on the hard drive (Dropbox/minxss\_dropbox/isis\_rundirs)
   1. Note: All passes in a day go into the same ISIS yyyy\_doy\_hh\_mm\_ss folder but a new .out file is generated each time ISIS opens or when it is commanded to rollover the telemetry file
   2. You can just copy the whole yyyy\_doy\_hh\_mm\_ss folder as long as you **make sure to replace all files**; **the dialogue box that asks you about this often appears behind all other windows**
7. On the DataProcessing computer (iMac MacL68), run *minxss\_read\_packets.pro* in IDL on the new telemetry file
8. Then run *minxss\_make\_level0b.pro* on the result of the previous step (a .sav file)
9. Then run *minxss\_make\_level0c.pro* on the result of the previous step (another .sav file)
10. Then run *minxss\_plots\_trends.pro, minxss\_plots\_power.pro* on the result of the previous step
11. If appropriate, run *minxss\_plots\_adcs.pro* as well
12. Colden: Run python scripts to populate/update the packet database (or email Colden if he’s not there)

* Phase 1: IS-1 checkout
* Verify we can establish communication (No Hello-IS1 script required, since satellite beacons autonomously, receiving beacon is a proof of telemetry link) Hello-IS1 created
* Check aliveness (PHOENIX or SAFE)
* Transition to safe (should be autonomous if power positive)
* Stop Solar Panel and Antenna Deployments
* Reset Launch Delay Threshold

* Phase 2: Spacecraft commissioning
  + Set s/c and ADCS time
    - * Update the ADCS time with current time
  + Playback deployment data
  + Load ephemeris and test fine point

* Phase 3: Instrument commissioning
  + Instrument aliveness
  + Transition to science mode

**Note**: Contingency Management Plan to be worked out.

1. Scenarios for sending S/C Reset Command. (This is a reset of the complete spacecraft)
2. Scenarios for Turning ON/OFF any particular subsystem. Following subsystems can be turned OFF via command:
   1. DAXSS
   2. CIP
   3. ADCS
   4. S-BAND
   5. Heater

**Phase 1**

**GOALS**

* Verify communication
* Bus is working and is power positive

Sequence of Post Launch Operations:

1. When beacons are received during the first pass, check the mode.
   1. If SAFE: Run Commissioning\_Aliveness\_SAFE
   2. If Phoenix: Run Commissioning\_Aliveness\_Phoenix
   3. If Neither : (Contingency mode, try putting S/C in SAFE mode)

Scripts

1. **Hello\_IS1:** Script to keep waiting for the first beacon to arrive from IS-1
2. **Commission\_aliveness\_safe** script does the following:
   1. Set Beacon Packets to UHF with Rate = 3 Seconds
   2. Confirm if the satellite is in SAFE mode, If not set it to SAFE mode manually
   3. Perform Telemetry Checks
      1. commission\_cdh\_tlm\_check
      2. commission\_eps\_tlm\_check
      3. commission\_comm\_tlm\_check
      4. commission\_adcs\_tlm\_check
   4. Reset launch delay counter
      * 1. First Enable mode\_hk packet to verify status of deployments.
      1. Once the s/c has launched and the initial long delay has elapsed, ground should send a command to set the delay to ten seconds to prevent another large delay upon s/c reset.
      2. Verify launch delay from mode\_hk packet
   5. Set Launch Delay Counter
      1. UHF Deployment: Can be cancelled since beacons are being received
      2. Solar Panel Deployments: Check Panel Current (display the currents and operator can proceed accordingly), IF current are above (??), Cancel the deployments
      3. Verify deployment flags from the mode\_hk packet
      4. Disable mode\_hk packet
   6. Set Beacon Packets to UHF with Rate = 30 Seconds

1. **Commission\_aliveness\_phoenix** script does the following:
   * 1. Set Beacon Packets to UHF with Rate = 3 Seconds
     2. Confirm if the satellite is in Phoenix mode
     3. Perform Telemetry Checks
     4. commission\_cdh\_tlm\_check
     5. commission\_eps\_tlm\_check
     6. commission\_comm\_tlm\_check

1. Cancel Deployment Retries
   1. First Enable Mode\_HK packet to verify status of deployments.
   2. UHF Deployment: Can be cancelled since deployments are being received
   3. Solar Panel Deployments:
      1. Check Panel Voltages: IF voltages are above (??), Cancel the deployments
   4. Verify deployment flags from the mode\_hk packet
2. Set Launch Delay Counter
   1. Once the s/c has launched and the initial long delay has elapsed, ground should send a command to set the delay to zero to prevent another delay upon s/c reset.
   2. Disable mode\_hk packet
3. Set Beacon Packets to UHF with Rate = 30 Seconds

**Phase 2:**

1. Commission the s/c
2. Commission\_set\_spacecraft\_time
   1. Set DAXSS time in this script
   2. Look at MINXSS set time script
3. Commission\_set\_adcs\_time
   1. Use cmd\_adcs\_Time\_SetCurrentTimeUtc
   2. Grab system time through a different short method
4. Commission ADCS
   1. Commission\_set\_ephemeris
      1. Ephemeris would typically persist for long (around 1 month)
      2. Check on a repass if the satellite is in fine point, if not then reload a new ephemeris
      3. May be a good thing to upload latest time to DAXSS as well
   2. Commission\_test\_fine\_point
      1. Go to fine sun point ? either sun point or fine point. what is fine sun point?
      2. Check solar panel values/ ADCS telemetry adcs\_att\_cmd\_adcs\_mode should go to 1/ FINE\_POINT
5. Playback deployment data – depends on time since launch
   1. Pass the partition number and previous write pointer as an argument to the code
   2. Captures the current write pointer for beacon partition
   3. Downloads data in bursts of 300 packets in timeout of 10 seconds.
   4. Also has an option to download contiguous data at a timeout of 5 minutes instead
6. Point the satellite to IIST Ground station:
   1. There are 3 different possible commands to ADCS in addition to pass through commands for tracking:
      1. Cmd\_adcs\_coarse\_point – Coarse sun pointing
      2. Cmd\_adcs\_fine\_point – Fine sun pointing
      3. Cmd\_adcs\_ram\_point – Ram pointing.

Additional commands to update fine and ram pointing directions – what is the scope of these commands? When are these to be used?

* + 1. Cmd\_adcs\_fine\_update
    2. Cmd\_adcs\_ram\_update

Could use the command cmd\_adcs\_AttCmd\_GotoEcefPoint – to stare at IIST ground station during pass.

The pass through command to ADCS is given as:

cmd\_adcs\_pass len <length> data <command data>

* 1. Do we ever download star tracker image?

**Phase 3**

Checkout instruments

1. Commission\_instrument\_aliveness\_DAXSS
2. Commission\_science\_mode
3. Commission\_x123\_threshold
4. Commission\_instrument\_aliveness\_CIP
   1. Check with Amal for CIP team for CIP commissioning
   2. CIP\_test
   3. Regular operations of CIP in one of the modes

1. In sun-point mode, XACT tries to keep the rates to 0 based on the IMU, but the IMU itself has a bias of about 0.2º/sec, which won’t be corrected [↑](#footnote-ref-1)
2. XACT can accept a command to increase this roll rate, but it can’t get any lower than this default [↑](#footnote-ref-2)